

Outline

- 1 Fundamental group: definition
- 2 Fundamental group: computation
- 3 Fundamental group: applications



Homotopy

Definition 1 (Path; Definition 4 of Lecture 5)

Let A be a topological space and let $x, y \in A$. A **path** from x_0 to x_1 is a continuous map $f : [0, 1] \rightarrow A$ such that $f(0) = x_0$ and $f(1) = x_1$.

Definition 1 (Path; Definition 4 of Lecture 5)

Let A be a topological space and let $x, y \in A$. A **path** from x_0 to x_1 is a continuous map $f : [0, 1] \rightarrow A$ such that $f(0) = x_0$ and $f(1) = x_1$.

Definition 2

A **homotopy** of paths is the family of paths $f_t : [0, 1] \rightarrow A$, $0 \leq t \leq 1$, such that

Definition 1 (Path; Definition 4 of Lecture 5)

Let A be a topological space and let $x, y \in A$. A **path** from x_0 to x_1 is a continuous map $f : [0, 1] \rightarrow A$ such that $f(0) = x_0$ and $f(1) = x_1$.

Definition 2

A **homotopy** of paths is the family of paths $f_t : [0, 1] \rightarrow A$, $0 \leq t \leq 1$, such that

- The endpoints $f_t(0) = x_0$ and $f_t(1) = x_1$ are independent of t ;

Definition 1 (Path; Definition 4 of Lecture 5)

Let A be a topological space and let $x, y \in A$. A **path** from x_0 to x_1 is a continuous map $f : [0, 1] \rightarrow A$ such that $f(0) = x_0$ and $f(1) = x_1$.

Definition 2

A **homotopy** of paths is the family of paths $f_t : [0, 1] \rightarrow A$, $0 \leq t \leq 1$, such that

- The endpoints $f_t(0) = x_0$ and $f_t(1) = x_1$ are independent of t ;
- The associated map $F : [0, 1] \times [0, 1] \rightarrow A$ defined by $F(s, t) = f_t(s)$ is continuous.

Definition 1 (Path; Definition 4 of Lecture 5)

Let A be a topological space and let $x, y \in A$. A **path** from x_0 to x_1 is a continuous map $f : [0, 1] \rightarrow A$ such that $f(0) = x_0$ and $f(1) = x_1$.

Definition 2

A **homotopy** of paths is the family of paths $f_t : [0, 1] \rightarrow A$, $0 \leq t \leq 1$, such that

- The endpoints $f_t(0) = x_0$ and $f_t(1) = x_1$ are independent of t ;
- The associated map $F : [0, 1] \times [0, 1] \rightarrow A$ defined by $F(s, t) = f_t(s)$ is continuous.

Homotopy

Definition 1 (Path; Definition 4 of Lecture 5)

Let A be a topological space and let $x, y \in A$. A **path** from x_0 to x_1 is a continuous map $f : [0, 1] \rightarrow A$ such that $f(0) = x_0$ and $f(1) = x_1$.

Definition 2

A **homotopy** of paths is the family of paths $f_t : [0, 1] \rightarrow A$, $0 \leq t \leq 1$, such that

- The endpoints $f_t(0) = x_0$ and $f_t(1) = x_1$ are independent of t ;
- The associated map $F : [0, 1] \times [0, 1] \rightarrow A$ defined by $F(s, t) = f_t(s)$ is continuous.

Two paths f_0 and f_1 connected by a homotopy are called **homotopic**;

Homotopy

Definition 1 (Path; Definition 4 of Lecture 5)

Let A be a topological space and let $x, y \in A$. A **path** from x_0 to x_1 is a continuous map $f : [0, 1] \rightarrow A$ such that $f(0) = x_0$ and $f(1) = x_1$.

Definition 2

A **homotopy** of paths is the family of paths $f_t : [0, 1] \rightarrow A$, $0 \leq t \leq 1$, such that

- The endpoints $f_t(0) = x_0$ and $f_t(1) = x_1$ are independent of t ;
- The associated map $F : [0, 1] \times [0, 1] \rightarrow A$ defined by $F(s, t) = f_t(s)$ is continuous.

Two paths f_0 and f_1 connected by a homotopy are called **homotopic**; notation: $f_0 \simeq f_1$.

Homotopy

Definition 1 (Path; Definition 4 of Lecture 5)

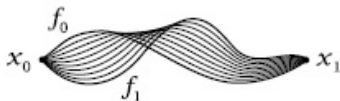
Let A be a topological space and let $x, y \in A$. A **path** from x_0 to x_1 is a continuous map $f : [0, 1] \rightarrow A$ such that $f(0) = x_0$ and $f(1) = x_1$.

Definition 2

A **homotopy** of paths is the family of paths $f_t : [0, 1] \rightarrow A$, $0 \leq t \leq 1$, such that

- The endpoints $f_t(0) = x_0$ and $f_t(1) = x_1$ are independent of t ;
- The associated map $F : [0, 1] \times [0, 1] \rightarrow A$ defined by $F(s, t) = f_t(s)$ is continuous.

Two paths f_0 and f_1 connected by a homotopy are called **homotopic**; notation: $f_0 \simeq f_1$.



Examples

Examples

Intuitively: you can continuously deform the path f_0 to the path f_1 .

Examples

Intuitively: you can continuously deform the path f_0 to the path f_1 .

Example 1

In \mathbb{R}^n , any two paths with common endpoints are homotopic:

Examples

Intuitively: you can continuously deform the path f_0 to the path f_1 .

Example 1

In \mathbb{R}^n , any two paths with common endpoints are homotopic:

$$F(s, t) = (1 - t)f_0(s) + tf_1(s).$$

Examples

Intuitively: you can continuously deform the path f_0 to the path f_1 .

Example 1

In \mathbb{R}^n , any two paths with common endpoints are homotopic:

$$F(s, t) = (1 - t)f_0(s) + tf_1(s).$$

On a sphere S^n , $n > 1$, any two paths are homotopic.

Examples

Intuitively: you can continuously deform the path f_0 to the path f_1 .

Example 1

In \mathbb{R}^n , any two paths with common endpoints are homotopic:

$$F(s, t) = (1 - t)f_0(s) + tf_1(s).$$

On a sphere S^n , $n > 1$, any two paths are homotopic.

On S^1 (or in $\mathbb{R}^2 \setminus \{0\}$), there are non-homotopic paths.

Examples

Intuitively: you can continuously deform the path f_0 to the path f_1 .

Example 1

In \mathbb{R}^n , any two paths with common endpoints are homotopic:

$$F(s, t) = (1 - t)f_0(s) + tf_1(s).$$

On a sphere S^n , $n > 1$, any two paths are homotopic.

On S^1 (or in $\mathbb{R}^2 \setminus \{0\}$), there are non-homotopic paths.

On a torus, the parallels and the meridians are not homotopic.

Examples

Intuitively: you can continuously deform the path f_0 to the path f_1 .

Example 1

In \mathbb{R}^n , any two paths with common endpoints are homotopic:

$$F(s, t) = (1 - t)f_0(s) + tf_1(s).$$

On a sphere S^n , $n > 1$, any two paths are homotopic.

On S^1 (or in $\mathbb{R}^2 \setminus \{0\}$), there are non-homotopic paths.

On a torus, the parallels and the meridians are not homotopic.

Examples

Intuitively: you can continuously deform the path f_0 to the path f_1 .

Example 1

In \mathbb{R}^n , any two paths with common endpoints are homotopic:

$$F(s, t) = (1 - t)f_0(s) + tf_1(s).$$

On a sphere S^n , $n > 1$, any two paths are homotopic.

On S^1 (or in $\mathbb{R}^2 \setminus \{0\}$), there are non-homotopic paths.

On a torus, the parallels and the meridians are not homotopic.

Definition 3 (Reparametrisation)

A reparametrisation of a path $f : [0, 1] \rightarrow A$ is a path $f\phi$, where

$\phi : [0, 1] \rightarrow [0, 1]$ is a continuous function with $\phi(0) = 0$ and $\phi(1) = 1$.

Examples

Intuitively: you can continuously deform the path f_0 to the path f_1 .

Example 1

In \mathbb{R}^n , any two paths with common endpoints are homotopic:

$$F(s, t) = (1 - t)f_0(s) + tf_1(s).$$

On a sphere S^n , $n > 1$, any two paths are homotopic.

On S^1 (or in $\mathbb{R}^2 \setminus \{0\}$), there are non-homotopic paths.

On a torus, the parallels and the meridians are not homotopic.

Definition 3 (Reparametrisation)

A reparametrisation of a path $f : [0, 1] \rightarrow A$ is a path $f\phi$, where

$\phi : [0, 1] \rightarrow [0, 1]$ is a continuous function with $\phi(0) = 0$ and $\phi(1) = 1$.

Lemma 1

A path is homotopic to its reparametrisation.

Examples

Intuitively: you can continuously deform the path f_0 to the path f_1 .

Example 1

In \mathbb{R}^n , any two paths with common endpoints are homotopic:

$$F(s, t) = (1 - t)f_0(s) + tf_1(s).$$

On a sphere S^n , $n > 1$, any two paths are homotopic.

On S^1 (or in $\mathbb{R}^2 \setminus \{0\}$), there are non-homotopic paths.

On a torus, the parallels and the meridians are not homotopic.

Definition 3 (Reparametrisation)

A reparametrisation of a path $f : [0, 1] \rightarrow A$ is a path $f\phi$, where

$\phi : [0, 1] \rightarrow [0, 1]$ is a continuous function with $\phi(0) = 0$ and $\phi(1) = 1$.

Lemma 1

A path is homotopic to its reparametrisation.

Proof.

$$F(s, t) = f((1 - t)s + t\phi(s)).$$



Lemma 2

" \simeq " is an equivalence relation on the set of paths with fixed endpoints.

Homotopy classes

Lemma 2

" \simeq " is an equivalence relation on the set of paths with fixed endpoints.

Proof.

Reflexivity is obvious: $F(s, t) = f(s)$.

Lemma 2

" \simeq " is an equivalence relation on the set of paths with fixed endpoints.

Proof.

Reflexivity is obvious: $F(s, t) = f(s)$. Symmetry is easy: if $F(s, t)$ is a homotopy that joins f_0 to f_1 , then $G(s, t) = F(s, 1 - t)$ is a homotopy that joins f_1 to f_0 .

Lemma 2

" \simeq " is an equivalence relation on the set of paths with fixed endpoints.

Proof.

Reflexivity is obvious: $F(s, t) = f(s)$. Symmetry is easy: if $F(s, t)$ is a homotopy that joins f_0 to f_1 , then $G(s, t) = F(s, 1 - t)$ is a homotopy that joins f_1 to f_0 . To prove transitivity, suppose that $F(s, t)$ is a homotopy that joins f_0 to f_1 , and $G(s, t)$ is a homotopy that joins f_1 to f_2 .

Lemma 2

" \simeq " is an equivalence relation on the set of paths with fixed endpoints.

Proof.

Reflexivity is obvious: $F(s, t) = f(s)$. Symmetry is easy: if $F(s, t)$ is a homotopy that joins f_0 to f_1 , then $G(s, t) = F(s, 1 - t)$ is a homotopy that joins f_1 to f_0 . To prove transitivity, suppose that $F(s, t)$ is a homotopy that joins f_0 to f_1 , and $G(s, t)$ is a homotopy that joins f_1 to f_2 .

Then $H(s, t) = \begin{cases} F(s, 2t) & \text{if } t \in [0, \frac{1}{2}] \\ G(s, 2t - 1) & \text{if } t \in [\frac{1}{2}, 1] \end{cases}$ is a homotopy between f_0 and f_2 .

Lemma 2

" \simeq " is an equivalence relation on the set of paths with fixed endpoints.

Proof.

Reflexivity is obvious: $F(s, t) = f(s)$. Symmetry is easy: if $F(s, t)$ is a homotopy that joins f_0 to f_1 , then $G(s, t) = F(s, 1 - t)$ is a homotopy that joins f_1 to f_0 . To prove transitivity, suppose that $F(s, t)$ is a homotopy that joins f_0 to f_1 , and $G(s, t)$ is a homotopy that joins f_1 to f_2 .

Then $H(s, t) = \begin{cases} F(s, 2t) & \text{if } t \in [0, \frac{1}{2}] \\ G(s, 2t - 1) & \text{if } t \in [\frac{1}{2}, 1] \end{cases}$ is a homotopy between f_0 and f_2 . H is continuous by Theorem 5 of Lecture 4. □

Lemma 2

" \simeq " is an equivalence relation on the set of paths with fixed endpoints.

Proof.

Reflexivity is obvious: $F(s, t) = f(s)$. Symmetry is easy: if $F(s, t)$ is a homotopy that joins f_0 to f_1 , then $G(s, t) = F(s, 1 - t)$ is a homotopy that joins f_1 to f_0 . To prove transitivity, suppose that $F(s, t)$ is a homotopy that joins f_0 to f_1 , and $G(s, t)$ is a homotopy that joins f_1 to f_2 .

Then $H(s, t) = \begin{cases} F(s, 2t) & \text{if } t \in [0, \frac{1}{2}] \\ G(s, 2t - 1) & \text{if } t \in [\frac{1}{2}, 1] \end{cases}$ is a homotopy between f_0 and f_2 . H is continuous by Theorem 5 of Lecture 4. □

The equivalence class $[f]$ of a paths f is called the **homotopy class** of f .

Product of paths

Product of paths

Definition 4 (Product of paths; Question 1(b) of Assignment 2)

Suppose $f, g : [0, 1] \rightarrow A$ are paths such that $f(1) = g(0)$. Then **the product** of the paths f and g is the path $h = f \circ g$ defined by

$$h : [0, 1] \rightarrow A : s \mapsto \begin{cases} f(2s) & : s \in [0, \frac{1}{2}], \\ g(2s - 1) & : s \in [\frac{1}{2}, 1]. \end{cases}$$

Product of paths

Definition 4 (Product of paths; Question 1(b) of Assignment 2)

Suppose $f, g : [0, 1] \rightarrow A$ are paths such that $f(1) = g(0)$. Then **the product** of the paths f and g is the path $h = f \circ g$ defined by

$$h : [0, 1] \rightarrow A : s \mapsto \begin{cases} f(2s) & : s \in [0, \frac{1}{2}], \\ g(2s - 1) & : s \in [\frac{1}{2}, 1]. \end{cases}$$

Lemma 3

The product operation respects homotopy classes, that is, if $f_0 \simeq f_1$ and $g_0 \simeq g_1$, then $f_0 \circ g_0 \simeq f_1 \circ g_1$.

Proof: exercise.

Product of paths

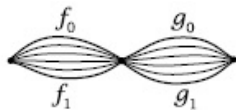
Definition 4 (Product of paths; Question 1(b) of Assignment 2)

Suppose $f, g : [0, 1] \rightarrow A$ are paths such that $f(1) = g(0)$. Then **the product** of the paths f and g is the path $h = f \circ g$ defined by

$$h : [0, 1] \rightarrow A : s \mapsto \begin{cases} f(2s) & : s \in [0, \frac{1}{2}], \\ g(2s - 1) & : s \in [\frac{1}{2}, 1]. \end{cases}$$

Lemma 3

The product operation respects homotopy classes, that is, if $f_0 \simeq f_1$ and $g_0 \simeq g_1$, then $f_0 \circ g_0 \simeq f_1 \circ g_1$.



Proof: exercise.

Fundamental group

Fundamental group

We restrict attention to paths $f : [0, 1] \rightarrow A$ with the same starting and ending point $f(0) = f(1) = x_0 \in A$. Such paths are called **loops**, and the point x_0 **the basepoint**.

Fundamental group

We restrict attention to paths $f : [0, 1] \rightarrow A$ with the same starting and ending point $f(0) = f(1) = x_0 \in A$. Such paths are called **loops**, and the point x_0 **the basepoint**.

Definition 5 (Fundamental group; Henri Poincaré, 1895)

The set $\pi_1(A, x_0)$ of all homotopy classes $[f]$ of loops $f : [0, 1] \rightarrow A$ at the basepoint x_0 is called the **fundamental group** of A at x_0 .

Fundamental group

We restrict attention to paths $f : [0, 1] \rightarrow A$ with the same starting and ending point $f(0) = f(1) = x_0 \in A$. Such paths are called **loops**, and the point x_0 **the basepoint**.

Definition 5 (Fundamental group; Henri Poincaré, 1895)

The set $\pi_1(A, x_0)$ of all homotopy classes $[f]$ of loops $f : [0, 1] \rightarrow A$ at the basepoint x_0 is called the **fundamental group** of A at x_0 .

Theorem 1

$\pi_1(A, x_0)$ is a group with respect to the product $[f][g] = [f \circ g]$.

Fundamental group

We restrict attention to paths $f : [0, 1] \rightarrow A$ with the same starting and ending point $f(0) = f(1) = x_0 \in A$. Such paths are called **loops**, and the point x_0 **the basepoint**.

Definition 5 (Fundamental group; Henri Poincaré, 1895)

The set $\pi_1(A, x_0)$ of all homotopy classes $[f]$ of loops $f : [0, 1] \rightarrow A$ at the basepoint x_0 is called the **fundamental group** of A at x_0 .

Theorem 1

$\pi_1(A, x_0)$ is a group with respect to the product $[f][g] = [f \circ g]$.

Proof.

Fundamental group

We restrict attention to paths $f : [0, 1] \rightarrow A$ with the same starting and ending point $f(0) = f(1) = x_0 \in A$. Such paths are called **loops**, and the point x_0 **the basepoint**.

Definition 5 (Fundamental group; Henri Poincaré, 1895)

The set $\pi_1(A, x_0)$ of all homotopy classes $[f]$ of loops $f : [0, 1] \rightarrow A$ at the basepoint x_0 is called the **fundamental group** of A at x_0 .

Theorem 1

$\pi_1(A, x_0)$ is a group with respect to the product $[f][g] = [f \circ g]$.

Proof.

- 1 First, $f \circ g$ is well-defined, as both f and g are loops.

Fundamental group

We restrict attention to paths $f : [0, 1] \rightarrow A$ with the same starting and ending point $f(0) = f(1) = x_0 \in A$. Such paths are called **loops**, and the point x_0 **the basepoint**.

Definition 5 (Fundamental group; Henri Poincaré, 1895)

The set $\pi_1(A, x_0)$ of all homotopy classes $[f]$ of loops $f : [0, 1] \rightarrow A$ at the basepoint x_0 is called the **fundamental group** of A at x_0 .

Theorem 1

$\pi_1(A, x_0)$ is a group with respect to the product $[f][g] = [f \circ g]$.

Proof.

- 1 First, $f \circ g$ is well-defined, as both f and g are loops. Second, $[f][g]$ is well-defined by Lemma 3.

Fundamental group

We restrict attention to paths $f : [0, 1] \rightarrow A$ with the same starting and ending point $f(0) = f(1) = x_0 \in A$. Such paths are called **loops**, and the point x_0 **the basepoint**.

Definition 5 (Fundamental group; Henri Poincaré, 1895)

The set $\pi_1(A, x_0)$ of all homotopy classes $[f]$ of loops $f : [0, 1] \rightarrow A$ at the basepoint x_0 is called the **fundamental group** of A at x_0 .

Theorem 1

$\pi_1(A, x_0)$ is a group with respect to the product $[f][g] = [f \circ g]$.

Proof.

- 1 First, $f \circ g$ is well-defined, as both f and g are loops. Second, $[f][g]$ is well-defined by Lemma 3.
- 2 To prove the theorem we need to verify the axioms of the group: associativity, identity and inverse.

Proof continued

Proof continued

- ③ For three loops f, g, h with the same basepoint we have $(f \circ g) \circ h \simeq f \circ (g \circ h)$ by reparametrisation on the right and hence by Lemma 1.

- ③ For three loops f, g, h with the same basepoint we have $(f \circ g) \circ h \simeq f \circ (g \circ h)$ by reparametrisation on the right and hence by Lemma 1. So the product is **associative**.

- ③ For three loops f, g, h with the same basepoint we have $(f \circ g) \circ h \simeq f \circ (g \circ h)$ by reparametrisation on the right and hence by Lemma 1. So the product is **associative**.



- 3 For three loops f, g, h with the same basepoint we have $(f \circ g) \circ h \simeq f \circ (g \circ h)$ by reparametrisation on the right and hence by Lemma 1. So the product is **associative**.



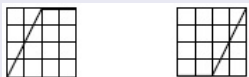
- 4 Define **the identity** e to be the class of the constant map $c : [0, 1] \rightarrow A$, $c(s) = x_0$. Then for a loop f we have $c \circ f \cong f \circ c \cong f$ by reparametrisations below and hence by Lemma 1.



- ③ For three loops f, g, h with the same basepoint we have $(f \circ g) \circ h \simeq f \circ (g \circ h)$ by reparametrisation on the right and hence by Lemma 1. So the product is **associative**.



- ④ Define **the identity** e to be the class of the constant map $c : [0, 1] \rightarrow A$, $c(s) = x_0$. Then for a loop f we have $c \circ f \cong f \circ c \cong f$ by reparametrisations below and hence by Lemma 1.

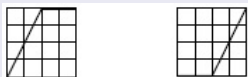


- ⑤ For a loop f we define the inverse loop \bar{f} by $\bar{f}(t) = f(1 - t)$.

- ③ For three loops f, g, h with the same basepoint we have $(f \circ g) \circ h \simeq f \circ (g \circ h)$ by reparametrisation on the right and hence by Lemma 1. So the product is **associative**.



- ④ Define **the identity** e to be the class of the constant map $c : [0, 1] \rightarrow A$, $c(s) = x_0$. Then for a loop f we have $c \circ f \cong f \circ c \cong f$ by reparametrisations below and hence by Lemma 1.

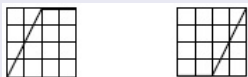


- ⑤ For a loop f we define the inverse loop \bar{f} by $\bar{f}(t) = f(1 - t)$. Then $f \circ \bar{f}$ and $\bar{f} \circ f$ both contract to c "along themselves".

- 3 For three loops f, g, h with the same basepoint we have $(f \circ g) \circ h \simeq f \circ (g \circ h)$ by reparametrisation on the right and hence by Lemma 1. So the product is **associative**.



- 4 Define **the identity** e to be the class of the constant map $c : [0, 1] \rightarrow A$, $c(s) = x_0$. Then for a loop f we have $f \circ c \cong f \circ c \cong f$ by reparametrisations below and hence by Lemma 1.



- 5 For a loop f we define the inverse loop \bar{f} by $\bar{f}(t) = f(1 - t)$. Then $f \circ \bar{f}$ and $\bar{f} \circ f$ both contract to c "along themselves". So by Lemma 3, $[\bar{f}] = [f]^{-1}$, the **inverse** to $[f]$.



Dependence on the base point

Dependence on the base point

Let A be path-connected and let $x_0, x_1 \in A$.

Dependence on the base point

Let A be path-connected and let $x_0, x_1 \in A$.

Theorem 2

The groups $\pi_1(A, x_0)$ and $\pi_1(A, x_1)$ are isomorphic.

Dependence on the base point

Let A be path-connected and let $x_0, x_1 \in A$.

Theorem 2

The groups $\pi_1(A, x_0)$ and $\pi_1(A, x_1)$ are isomorphic.

Proof.

Let h be a path joining x_0 and x_1 .

Dependence on the base point

Let A be path-connected and let $x_0, x_1 \in A$.

Theorem 2

The groups $\pi_1(A, x_0)$ and $\pi_1(A, x_1)$ are isomorphic.

Proof.

Let h be a path joining x_0 and x_1 . Define the map $\beta_h : \pi_1(A, x_0) \rightarrow \pi_1(A, x_1)$ by $\beta_h[f] = [h \circ f \circ \bar{h}]$.

Dependence on the base point

Let A be path-connected and let $x_0, x_1 \in A$.

Theorem 2

The groups $\pi_1(A, x_0)$ and $\pi_1(A, x_1)$ are isomorphic.

Proof.

Let h be a path joining x_0 and x_1 . Define the map $\beta_h : \pi_1(A, x_0) \rightarrow \pi_1(A, x_1)$ by $\beta_h[f] = [h \circ f \circ \bar{h}]$. The map β_h is an isomorphism (exercise).

Dependence on the base point

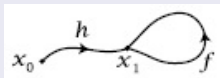
Let A be path-connected and let $x_0, x_1 \in A$.

Theorem 2

The groups $\pi_1(A, x_0)$ and $\pi_1(A, x_1)$ are isomorphic.

Proof.

Let h be a path joining x_0 and x_1 . Define the map $\beta_h : \pi_1(A, x_0) \rightarrow \pi_1(A, x_1)$ by $\beta_h[f] = [h \circ f \circ \bar{h}]$. The map β_h is an isomorphism (exercise).



Dependence on the base point

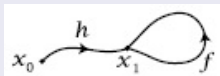
Let A be path-connected and let $x_0, x_1 \in A$.

Theorem 2

The groups $\pi_1(A, x_0)$ and $\pi_1(A, x_1)$ are isomorphic.

Proof.

Let h be a path joining x_0 and x_1 . Define the map $\beta_h : \pi_1(A, x_0) \rightarrow \pi_1(A, x_1)$ by $\beta_h[f] = [h \circ f \circ \bar{h}]$. The map β_h is an isomorphism (exercise).



So for a path connected space we can simply speak of $\pi_1(A)$.

Simply-connected spaces and the circle

Simply-connected spaces and the circle

A topological space A is called **simply-connected** if it is path-connected and $\pi_1(A) = 0$.

Simply-connected spaces and the circle

A topological space A is called **simply-connected** if it is path-connected and $\pi_1(A) = 0$.

The following spaces are simply-connected:

Simply-connected spaces and the circle

A topological space A is called **simply-connected** if it is path-connected and $\pi_1(A) = 0$.

The following spaces are simply-connected:

\mathbb{R}^n ,

Simply-connected spaces and the circle

A topological space A is called **simply-connected** if it is path-connected and $\pi_1(A) = 0$.

The following spaces are simply-connected:

\mathbb{R}^n , S^m , $m > 1$,

Simply-connected spaces and the circle

A topological space A is called **simply-connected** if it is path-connected and $\pi_1(A) = 0$.

The following spaces are simply-connected:

\mathbb{R}^n , S^m , $m > 1$, any convex subset of \mathbb{R}^n .

Simply-connected spaces and the circle

A topological space A is called **simply-connected** if it is path-connected and $\pi_1(A) = 0$.

The following spaces are simply-connected:

\mathbb{R}^n , S^m , $m > 1$, any convex subset of \mathbb{R}^n .

Theorem 3

$$\pi_1(S^1) = \mathbb{Z}.$$

Simply-connected spaces and the circle

A topological space A is called **simply-connected** if it is path-connected and $\pi_1(A) = 0$.

The following spaces are simply-connected:

\mathbb{R}^n , S^m , $m > 1$, any convex subset of \mathbb{R}^n .

Theorem 3

$$\pi_1(S^1) = \mathbb{Z}.$$

Proof.

Let $x_0 = (1, 0)$.

Simply-connected spaces and the circle

A topological space A is called **simply-connected** if it is path-connected and $\pi_1(A) = 0$.

The following spaces are simply-connected:

\mathbb{R}^n , S^m , $m > 1$, any convex subset of \mathbb{R}^n .

Theorem 3

$$\pi_1(S^1) = \mathbb{Z}.$$

Proof.

Let $x_0 = (1, 0)$. Define $p : \mathbb{R} \rightarrow S^1$ by $p(t) = (\cos(2\pi t), \sin(2\pi t))$.

Simply-connected spaces and the circle

A topological space A is called **simply-connected** if it is path-connected and $\pi_1(A) = 0$.

The following spaces are simply-connected:

\mathbb{R}^n , S^m , $m > 1$, any convex subset of \mathbb{R}^n .

Theorem 3

$$\pi_1(S^1) = \mathbb{Z}.$$

Proof.

Let $x_0 = (1, 0)$. Define $p : \mathbb{R} \rightarrow S^1$ by $p(t) = (\cos(2\pi t), \sin(2\pi t))$. To a path $f : [0, 1] \rightarrow S^1$ there uniquely corresponds a continuous function $\tilde{f} : [0, 1] \rightarrow \mathbb{R}$ such that $p(\tilde{f}(t)) = f(t)$:

Simply-connected spaces and the circle

A topological space A is called **simply-connected** if it is path-connected and $\pi_1(A) = 0$.

The following spaces are simply-connected:

\mathbb{R}^n , S^m , $m > 1$, any convex subset of \mathbb{R}^n .

Theorem 3

$$\pi_1(S^1) = \mathbb{Z}.$$

Proof.

Let $x_0 = (1, 0)$. Define $p : \mathbb{R} \rightarrow S^1$ by $p(t) = (\cos(2\pi t), \sin(2\pi t))$. To a path $f : [0, 1] \rightarrow S^1$ there uniquely corresponds a continuous function $\tilde{f} : [0, 1] \rightarrow \mathbb{R}$ such that $p(\tilde{f}(t)) = f(t)$: for every t , $\tilde{f}(t)$ is defined up to an integer, which we choose in such a way that \tilde{f} is continuous.

Simply-connected spaces and the circle

A topological space A is called **simply-connected** if it is path-connected and $\pi_1(A) = 0$.

The following spaces are simply-connected:

\mathbb{R}^n , S^m , $m > 1$, any convex subset of \mathbb{R}^n .

Theorem 3

$$\pi_1(S^1) = \mathbb{Z}.$$

Proof.

Let $x_0 = (1, 0)$. Define $p : \mathbb{R} \rightarrow S^1$ by $p(t) = (\cos(2\pi t), \sin(2\pi t))$. To a path $f : [0, 1] \rightarrow S^1$ there uniquely corresponds a continuous function $\tilde{f} : [0, 1] \rightarrow \mathbb{R}$ such that $p(\tilde{f}(t)) = f(t)$: for every t , $\tilde{f}(t)$ is defined up to an integer, which we choose in such a way that \tilde{f} is continuous.

Then $\tilde{f}(1)$ is an integer, the *winding number*.

Simply-connected spaces and the circle

A topological space A is called **simply-connected** if it is path-connected and $\pi_1(A) = 0$.

The following spaces are simply-connected:

\mathbb{R}^n , S^m , $m > 1$, any convex subset of \mathbb{R}^n .

Theorem 3

$$\pi_1(S^1) = \mathbb{Z}.$$

Proof.

Let $x_0 = (1, 0)$. Define $p : \mathbb{R} \rightarrow S^1$ by $p(t) = (\cos(2\pi t), \sin(2\pi t))$. To a path $f : [0, 1] \rightarrow S^1$ there uniquely corresponds a continuous function $\tilde{f} : [0, 1] \rightarrow \mathbb{R}$ such that $p(\tilde{f}(t)) = f(t)$: for every t , $\tilde{f}(t)$ is defined up to an integer, which we choose in such a way that \tilde{f} is continuous.

Then $\tilde{f}(1)$ is an integer, the *winding number*. The map $[f] \mapsto \tilde{f}(1)$ is an isomorphism. □

Fundamental Theorem of Algebra

Fundamental Theorem of Algebra

Theorem 4 (Fundamental Theorem of Algebra)

Any nonconstant polynomial in \mathbb{C} has a root.

Fundamental Theorem of Algebra

Theorem 4 (Fundamental Theorem of Algebra)

Any nonconstant polynomial in \mathbb{C} has a root.

Proof.

Let $p(z) = z^n + a_1 z^{n-1} + \cdots + a_{n-1} z + a_n$ have no roots.

Fundamental Theorem of Algebra

Theorem 4 (Fundamental Theorem of Algebra)

Any nonconstant polynomial in \mathbb{C} has a root.

Proof.

Let $p(z) = z^n + a_1 z^{n-1} + \cdots + a_{n-1} z + a_n$ have no roots. For $r \geq 0$

define $f_r(s) = \frac{p(re^{2\pi is})/p(r)}{|p(re^{2\pi is})/p(r)|}$.

Fundamental Theorem of Algebra

Theorem 4 (Fundamental Theorem of Algebra)

Any nonconstant polynomial in \mathbb{C} has a root.

Proof.

Let $p(z) = z^n + a_1 z^{n-1} + \cdots + a_{n-1} z + a_n$ have no roots. For $r \geq 0$ define $f_r(s) = \frac{p(re^{2\pi i s})/p(r)}{|p(re^{2\pi i s})/p(r)|}$. For a fixed r , $f_r : [0, 1] \rightarrow S^1$ is a loop with the basepoint at 1.

Fundamental Theorem of Algebra

Theorem 4 (Fundamental Theorem of Algebra)

Any nonconstant polynomial in \mathbb{C} has a root.

Proof.

Let $p(z) = z^n + a_1 z^{n-1} + \cdots + a_{n-1} z + a_n$ have no roots. For $r \geq 0$ define $f_r(s) = \frac{p(re^{2\pi i s})/p(r)}{|p(re^{2\pi i s})/p(r)|}$. For a fixed r , $f_r : [0, 1] \rightarrow S^1$ is a loop with the basepoint at 1. When r varies, the homotopy class $[f_r]$ doesn't change.

Fundamental Theorem of Algebra

Theorem 4 (Fundamental Theorem of Algebra)

Any nonconstant polynomial in \mathbb{C} has a root.

Proof.

Let $p(z) = z^n + a_1 z^{n-1} + \cdots + a_{n-1} z + a_n$ have no roots. For $r \geq 0$ define $f_r(s) = \frac{p(re^{2\pi i s})/p(r)}{|p(re^{2\pi i s})/p(r)|}$. For a fixed r , $f_r : [0, 1] \rightarrow S^1$ is a loop with the basepoint at 1. When r varies, the homotopy class $[f_r]$ doesn't change. As f_0 is trivial, $[f_r] = 0 \in \pi_1(S^1)$.

Fundamental Theorem of Algebra

Theorem 4 (Fundamental Theorem of Algebra)

Any nonconstant polynomial in \mathbb{C} has a root.

Proof.

Let $p(z) = z^n + a_1 z^{n-1} + \cdots + a_{n-1} z + a_n$ have no roots. For $r \geq 0$ define $f_r(s) = \frac{p(re^{2\pi i s})/p(r)}{|p(re^{2\pi i s})/p(r)|}$. For a fixed r , $f_r : [0, 1] \rightarrow S^1$ is a loop with the basepoint at 1. When r varies, the homotopy class $[f_r]$ doesn't change. As f_0 is trivial, $[f_r] = 0 \in \pi_1(S^1)$.

Take large $r > 1, \sum_i |a_i|$. Then for $|z| = r$ we have $|z|^n > |a_1 z^{n-1} + \cdots + a_{n-1} z + a_n|$.

Fundamental Theorem of Algebra

Theorem 4 (Fundamental Theorem of Algebra)

Any nonconstant polynomial in \mathbb{C} has a root.

Proof.

Let $p(z) = z^n + a_1 z^{n-1} + \cdots + a_{n-1} z + a_n$ have no roots. For $r \geq 0$ define $f_r(s) = \frac{p(re^{2\pi i s})/p(r)}{|p(re^{2\pi i s})/p(r)|}$. For a fixed r , $f_r : [0, 1] \rightarrow S^1$ is a loop with the basepoint at 1. When r varies, the homotopy class $[f_r]$ doesn't change. As f_0 is trivial, $[f_r] = 0 \in \pi_1(S^1)$.

Take large $r > 1, \sum_i |a_i|$. Then for $|z| = r$ we have $|z|^n > |a_1 z^{n-1} + \cdots + a_{n-1} z + a_n|$. So the polynomial $p_t(z) = z^n + t(a_1 z^{n-1} + \cdots + a_{n-1} z + a_n)$ has no roots on the circle $|z| = r$ for $t \in [0, 1]$.

Fundamental Theorem of Algebra

Theorem 4 (Fundamental Theorem of Algebra)

Any nonconstant polynomial in \mathbb{C} has a root.

Proof.

Let $p(z) = z^n + a_1 z^{n-1} + \cdots + a_{n-1} z + a_n$ have no roots. For $r \geq 0$ define $f_r(s) = \frac{p(re^{2\pi i s})/p(r)}{|p(re^{2\pi i s})/p(r)|}$. For a fixed r , $f_r : [0, 1] \rightarrow S^1$ is a loop with the basepoint at 1. When r varies, the homotopy class $[f_r]$ doesn't change. As f_0 is trivial, $[f_r] = 0 \in \pi_1(S^1)$.

Take large $r > 1, \sum_i |a_i|$. Then for $|z| = r$ we have $|z|^n > |a_1 z^{n-1} + \cdots + a_{n-1} z + a_n|$. So the polynomial $p_t(z) = z^n + t(a_1 z^{n-1} + \cdots + a_{n-1} z + a_n)$ has no roots on the circle $|z| = r$ for $t \in [0, 1]$. If we replace p by p_t in the formula for f_r we get a homotopy from f_r to the loop $\omega^n(s) = e^{2n\pi i s}$.

Fundamental Theorem of Algebra

Theorem 4 (Fundamental Theorem of Algebra)

Any nonconstant polynomial in \mathbb{C} has a root.

Proof.

Let $p(z) = z^n + a_1 z^{n-1} + \cdots + a_{n-1} z + a_n$ have no roots. For $r \geq 0$ define $f_r(s) = \frac{p(re^{2\pi i s})/p(r)}{|p(re^{2\pi i s})/p(r)|}$. For a fixed r , $f_r : [0, 1] \rightarrow S^1$ is a loop with the basepoint at 1. When r varies, the homotopy class $[f_r]$ doesn't change. As f_0 is trivial, $[f_r] = 0 \in \pi_1(S^1)$.

Take large $r > 1, \sum_i |a_i|$. Then for $|z| = r$ we have $|z|^n > |a_1 z^{n-1} + \cdots + a_{n-1} z + a_n|$. So the polynomial $p_t(z) = z^n + t(a_1 z^{n-1} + \cdots + a_{n-1} z + a_n)$ has no roots on the circle $|z| = r$ for $t \in [0, 1]$. If we replace p by p_t in the formula for f_r we get a homotopy from f_r to the loop $\omega^n(s) = e^{2n\pi i s}$. This loop has winding number n , that is $[f_r] = n$.

Fundamental Theorem of Algebra

Theorem 4 (Fundamental Theorem of Algebra)

Any nonconstant polynomial in \mathbb{C} has a root.

Proof.

Let $p(z) = z^n + a_1 z^{n-1} + \cdots + a_{n-1} z + a_n$ have no roots. For $r \geq 0$ define $f_r(s) = \frac{p(re^{2\pi i s})/p(r)}{|p(re^{2\pi i s})/p(r)|}$. For a fixed r , $f_r : [0, 1] \rightarrow S^1$ is a loop with the basepoint at 1. When r varies, the homotopy class $[f_r]$ doesn't change. As f_0 is trivial, $[f_r] = 0 \in \pi_1(S^1)$.

Take large $r > 1, \sum_i |a_i|$. Then for $|z| = r$ we have $|z|^n > |a_1 z^{n-1} + \cdots + a_{n-1} z + a_n|$. So the polynomial $p_t(z) = z^n + t(a_1 z^{n-1} + \cdots + a_{n-1} z + a_n)$ has no roots on the circle $|z| = r$ for $t \in [0, 1]$. If we replace p by p_t in the formula for f_r we get a homotopy from f_r to the loop $\omega^n(s) = e^{2n\pi i s}$. This loop has winding number n , that is $[f_r] = n$. From the above, $[f_r] = 0$, so f is a constant. □

Borsuk-Ulam Theorem

Theorem 5 (Borsuk-Ulam)

For every continuous map $f : S^2 \rightarrow \mathbb{R}^2$ there is a pair of antipodal points x and $-x$ such that $f(x) = f(-x)$.

Borsuk-Ulam Theorem

Theorem 5 (Borsuk-Ulam)

For every continuous map $f : S^2 \rightarrow \mathbb{R}^2$ there is a pair of antipodal points x and $-x$ such that $f(x) = f(-x)$.

See Bonus question in Assignment 3.

Proof.

Suppose not, then we can define $g : S^2 \rightarrow S^1$ by

$$g(x) = \frac{f(x) - f(-x)}{|f(x) - f(-x)|}.$$

Borsuk-Ulam Theorem

Theorem 5 (Borsuk-Ulam)

For every continuous map $f : S^2 \rightarrow \mathbb{R}^2$ there is a pair of antipodal points x and $-x$ such that $f(x) = f(-x)$.

See Bonus question in Assignment 3.

Proof.

Suppose not, then we can define $g : S^2 \rightarrow S^1$ by

$g(x) = \frac{f(x) - f(-x)}{|f(x) - f(-x)|}$. Let $\eta : [0, 1] \rightarrow S^2$ be defined by

$\eta(s) = (\cos(2\pi s), \sin(2\pi s), 0)$ and let $h = g\eta$.

Borsuk-Ulam Theorem

Theorem 5 (Borsuk-Ulam)

For every continuous map $f : S^2 \rightarrow \mathbb{R}^2$ there is a pair of antipodal points x and $-x$ such that $f(x) = f(-x)$.

See Bonus question in Assignment 3.

Proof.

Suppose not, then we can define $g : S^2 \rightarrow S^1$ by

$g(x) = \frac{f(x) - f(-x)}{|f(x) - f(-x)|}$. Let $\eta : [0, 1] \rightarrow S^2$ be defined by

$\eta(s) = (\cos(2\pi s), \sin(2\pi s), 0)$ and let $h = g\eta$. Then $h(s + \frac{1}{2}) = -h(s)$ for $s \in [0, \frac{1}{2}]$.

Borsuk-Ulam Theorem

Theorem 5 (Borsuk-Ulam)

For every continuous map $f : S^2 \rightarrow \mathbb{R}^2$ there is a pair of antipodal points x and $-x$ such that $f(x) = f(-x)$.

See Bonus question in Assignment 3.

Proof.

Suppose not, then we can define $g : S^2 \rightarrow S^1$ by

$g(x) = \frac{f(x) - f(-x)}{|f(x) - f(-x)|}$. Let $\eta : [0, 1] \rightarrow S^2$ be defined by

$\eta(s) = (\cos(2\pi s), \sin(2\pi s), 0)$ and let $h = g\eta$. Then $h(s + \frac{1}{2}) = -h(s)$

for $s \in [0, \frac{1}{2}]$. Moreover, lifting h to the map $\tilde{h} : [0, 1] \rightarrow \mathbb{R}$ we get

$\tilde{h}(s + \frac{1}{2}) = \tilde{h}(s) + \frac{q}{2}$ for some odd integer q and for all $s \in [0, \frac{1}{2}]$.

Borsuk-Ulam Theorem

Theorem 5 (Borsuk-Ulam)

For every continuous map $f : S^2 \rightarrow \mathbb{R}^2$ there is a pair of antipodal points x and $-x$ such that $f(x) = f(-x)$.

See Bonus question in Assignment 3.

Proof.

Suppose not, then we can define $g : S^2 \rightarrow S^1$ by

$g(x) = \frac{f(x) - f(-x)}{|f(x) - f(-x)|}$. Let $\eta : [0, 1] \rightarrow S^2$ be defined by

$\eta(s) = (\cos(2\pi s), \sin(2\pi s), 0)$ and let $h = g\eta$. Then $h(s + \frac{1}{2}) = -h(s)$

for $s \in [0, \frac{1}{2}]$. Moreover, lifting h to the map $\tilde{h} : [0, 1] \rightarrow \mathbb{R}$ we get

$\tilde{h}(s + \frac{1}{2}) = \tilde{h}(s) + \frac{q}{2}$ for some odd integer q and for all $s \in [0, \frac{1}{2}]$. q may depend on s , but it doesn't.

Borsuk-Ulam Theorem

Theorem 5 (Borsuk-Ulam)

For every continuous map $f : S^2 \rightarrow \mathbb{R}^2$ there is a pair of antipodal points x and $-x$ such that $f(x) = f(-x)$.

See Bonus question in Assignment 3.

Proof.

Suppose not, then we can define $g : S^2 \rightarrow S^1$ by

$g(x) = \frac{f(x) - f(-x)}{|f(x) - f(-x)|}$. Let $\eta : [0, 1] \rightarrow S^2$ be defined by

$\eta(s) = (\cos(2\pi s), \sin(2\pi s), 0)$ and let $h = g\eta$. Then $h(s + \frac{1}{2}) = -h(s)$

for $s \in [0, \frac{1}{2}]$. Moreover, lifting h to the map $\tilde{h} : [0, 1] \rightarrow \mathbb{R}$ we get

$\tilde{h}(s + \frac{1}{2}) = \tilde{h}(s) + \frac{q}{2}$ for some odd integer q and for all $s \in [0, \frac{1}{2}]$. q may depend on s , but it doesn't. But then $\tilde{h}(1) = \tilde{h}(0) + q$, so $[\tilde{h}] = q$ is odd.

Borsuk-Ulam Theorem

Theorem 5 (Borsuk-Ulam)

For every continuous map $f : S^2 \rightarrow \mathbb{R}^2$ there is a pair of antipodal points x and $-x$ such that $f(x) = f(-x)$.

See Bonus question in Assignment 3.

Proof.

Suppose not, then we can define $g : S^2 \rightarrow S^1$ by

$g(x) = \frac{f(x) - f(-x)}{|f(x) - f(-x)|}$. Let $\eta : [0, 1] \rightarrow S^2$ be defined by

$\eta(s) = (\cos(2\pi s), \sin(2\pi s), 0)$ and let $h = g\eta$. Then $h(s + \frac{1}{2}) = -h(s)$

for $s \in [0, \frac{1}{2}]$. Moreover, lifting h to the map $\tilde{h} : [0, 1] \rightarrow \mathbb{R}$ we get

$\tilde{h}(s + \frac{1}{2}) = \tilde{h}(s) + \frac{q}{2}$ for some odd integer q and for all $s \in [0, \frac{1}{2}]$. q may

depend on s , but it doesn't. But then $\tilde{h}(1) = \tilde{h}(0) + q$, so $[\tilde{h}] = q$ is odd.

On the other hand, \tilde{h} is null-homotopic, as η is. A contradiction. \square