

1 Quotient Spaces



Divide and Conquer

Consider a topological space (A, \mathcal{S}) , a set B and a map $f : A \rightarrow B$. Recall from Definition 4 of Lecture 4 that the set $\mathcal{T}_f = \{U \subset B : f^{-1}(U) \in \mathcal{S}\}$ is a topology on B , called the **final topology**, which makes f continuous.

Divide and Conquer

Consider a topological space (A, \mathcal{S}) , a set B and a map $f : A \rightarrow B$. Recall from Definition 4 of Lecture 4 that the set $\mathcal{T}_f = \{U \subset B : f^{-1}(U) \in \mathcal{S}\}$ is a topology on B , called the **final topology**, which makes f continuous.

Definition 1 (Quotient Topology)

Let (A, \mathcal{S}) be a topological space, let B be a set, and let $\pi : A \rightarrow B$ be an onto map. The final topology \mathcal{T}_π is called the **quotient topology** on B . The space (B, \mathcal{T}_π) is called a **quotient** of (A, \mathcal{S}) , and when there is no possible confusion, B is called a **quotient** of A . The map π is called the **quotient map** (it is sometimes also called the **natural projection map**).

Divide and Conquer

Consider a topological space (A, \mathcal{S}) , a set B and a map $f : A \rightarrow B$. Recall from Definition 4 of Lecture 4 that the set $\mathcal{T}_f = \{U \subset B : f^{-1}(U) \in \mathcal{S}\}$ is a topology on B , called the **final topology**, which makes f continuous.

Definition 1 (Quotient Topology)

Let (A, \mathcal{S}) be a topological space, let B be a set, and let $\pi : A \rightarrow B$ be an onto map. The final topology \mathcal{T}_π is called the **quotient topology** on B . The space (B, \mathcal{T}_π) is called a **quotient** of (A, \mathcal{S}) , and when there is no possible confusion, B is called a **quotient** of A . The map π is called the **quotient map** (it is sometimes also called the **natural projection map**).

Example 1

The map $\pi : \mathbb{R}^2 \rightarrow \mathbb{R} : (x, y) \mapsto x$ is a quotient map.

Divide and Conquer

Consider a topological space (A, \mathcal{S}) , a set B and a map $f : A \rightarrow B$. Recall from Definition 4 of Lecture 4 that the set $\mathcal{T}_f = \{U \subset B : f^{-1}(U) \in \mathcal{S}\}$ is a topology on B , called the **final topology**, which makes f continuous.

Definition 1 (Quotient Topology)

Let (A, \mathcal{S}) be a topological space, let B be a set, and let $\pi : A \rightarrow B$ be an onto map. The final topology \mathcal{T}_π is called the **quotient topology** on B . The space (B, \mathcal{T}_π) is called a **quotient** of (A, \mathcal{S}) , and when there is no possible confusion, B is called a **quotient** of A . The map π is called the **quotient map** (it is sometimes also called the **natural projection map**).

Example 1

The map $\pi : \mathbb{R}^2 \rightarrow \mathbb{R} : (x, y) \mapsto x$ is a quotient map.

Example 2

The map $f : \mathbb{R} \rightarrow \mathcal{S}^1 : x \mapsto e^{2\pi xi}$ is a quotient map.

Ready to collapse?

Quotients “collapse” chunks of a topological space. We need a way of saying which chunks. Recall from Lecture 1:

Definition 2 (Partition)

A set \mathcal{B} of non-empty subsets of A is called a **partition** of S provided

- 1 $(\forall x \in A)(\exists B \in \mathcal{B}) : x \in B$
- 2 $(\forall B, C \in \mathcal{B}) B \neq C \Rightarrow B \cap C = \emptyset$

Ready to collapse?

Quotients “collapse” chunks of a topological space. We need a way of saying which chunks. Recall from Lecture 1:

Definition 2 (Partition)

A set \mathcal{B} of non-empty subsets of A is called a **partition** of S provided

- 1 $(\forall x \in A)(\exists B \in \mathcal{B}) : x \in B$
- 2 $(\forall B, C \in \mathcal{B}) B \neq C \Rightarrow B \cap C = \emptyset$

(2) may be written in contrapositive form:

$$(2)' (\forall B, C \in \mathcal{B}) B \cap C \neq \emptyset \Rightarrow B = C.$$

(2) yields a unique $\pi : A \rightarrow \mathcal{B}$ such that $x \in \pi(x)$ and (1) shows that π is onto.

Ready to collapse?

Quotients “collapse” chunks of a topological space. We need a way of saying which chunks. Recall from Lecture 1:

Definition 2 (Partition)

A set \mathcal{B} of non-empty subsets of A is called a **partition** of S provided

- 1 $(\forall x \in A)(\exists B \in \mathcal{B}) : x \in B$
- 2 $(\forall B, C \in \mathcal{B}) B \neq C \Rightarrow B \cap C = \emptyset$

(2) may be written in contrapositive form:

$$(2)' (\forall B, C \in \mathcal{B}) B \cap C \neq \emptyset \Rightarrow B = C.$$

(2) yields a unique $\pi : A \rightarrow \mathcal{B}$ such that $x \in \pi(x)$ and (1) shows that π is onto.

Definition 3 (Natural Projection)

Let \mathcal{B} be a partition of A . The unique map $\pi : A \rightarrow \mathcal{B}$ such that $x \in \pi(x)$ is called the **natural projection** of A onto \mathcal{B} .

Partitions and equivalences

Conversely, if one is given an onto map $\pi : A \rightarrow B$ to some set B , then π determines a partition \mathcal{P} of A :

$$\mathcal{P} := \{\pi^{-1}(\{x\}) : x \in B\}.$$

Partitions and equivalences

Conversely, if one is given an onto map $\pi : A \rightarrow B$ to some set B , then π determines a partition \mathcal{P} of A :

$$\mathcal{P} := \{\pi^{-1}(\{x\}) : x \in B\}.$$

There is a third equivalent way of understanding partitions: this is by **equivalence relations**. Recall that a relation \sim on a set A is an equivalence relation if the following three conditions are satisfied:

Partitions and equivalences

Conversely, if one is given an onto map $\pi : A \rightarrow B$ to some set B , then π determines a partition \mathcal{P} of A :

$$\mathcal{P} := \{\pi^{-1}(\{x\}) : x \in B\}.$$

There is a third equivalent way of understanding partitions: this is by **equivalence relations**. Recall that a relation \sim on a set A is an equivalence relation if the following three conditions are satisfied:

- 1 $x \sim x$, for all $x \in A$ (reflexivity).

Partitions and equivalences

Conversely, if one is given an onto map $\pi : A \rightarrow B$ to some set B , then π determines a partition \mathcal{P} of A :

$$\mathcal{P} := \{\pi^{-1}(\{x\}) : x \in B\}.$$

There is a third equivalent way of understanding partitions: this is by **equivalence relations**. Recall that a relation \sim on a set A is an equivalence relation if the following three conditions are satisfied:

- 1 $x \sim x$, for all $x \in A$ (reflexivity).
- 2 $x \sim y \iff y \sim x$, for all $x, y \in A$ (symmetricity).

Partitions and equivalences

Conversely, if one is given an onto map $\pi : A \rightarrow B$ to some set B , then π determines a partition \mathcal{P} of A :

$$\mathcal{P} := \{\pi^{-1}(\{x\}) : x \in B\}.$$

There is a third equivalent way of understanding partitions: this is by **equivalence relations**. Recall that a relation \sim on a set A is an equivalence relation if the following three conditions are satisfied:

- 1 $x \sim x$, for all $x \in A$ (reflexivity).
- 2 $x \sim y \iff y \sim x$, for all $x, y \in A$ (symmetricity).
- 3 $x \sim y, y \sim z \implies x \sim z$, for all $x, y, z \in A$ (transitivity).

Partitions and equivalences

Conversely, if one is given an onto map $\pi : A \rightarrow B$ to some set B , then π determines a partition \mathcal{P} of A :

$$\mathcal{P} := \{\pi^{-1}(\{x\}) : x \in B\}.$$

There is a third equivalent way of understanding partitions: this is by **equivalence relations**. Recall that a relation \sim on a set A is an equivalence relation if the following three conditions are satisfied:

- 1 $x \sim x$, for all $x \in A$ (reflexivity).
- 2 $x \sim y \iff y \sim x$, for all $x, y \in A$ (symmetricity).
- 3 $x \sim y, y \sim z \implies x \sim z$, for all $x, y, z \in A$ (transitivity).

Partitions and equivalences

Conversely, if one is given an onto map $\pi : A \rightarrow B$ to some set B , then π determines a partition \mathcal{P} of A :

$$\mathcal{P} := \{\pi^{-1}(\{x\}) : x \in B\}.$$

There is a third equivalent way of understanding partitions: this is by **equivalence relations**. Recall that a relation \sim on a set A is an equivalence relation if the following three conditions are satisfied:

- 1 $x \sim x$, for all $x \in A$ (reflexivity).
- 2 $x \sim y \iff y \sim x$, for all $x, y \in A$ (symmetricity).
- 3 $x \sim y, y \sim z \implies x \sim z$, for all $x, y, z \in A$ (transitivity).

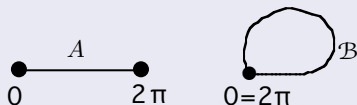
Given an equivalence relation and $x \in A$, the **equivalence class** $[x]$ is the set $[x] := \{y \in A : y \sim x\}$. Clearly, the set of equivalence classes forms a partition of A . Conversely, given a partition \mathcal{P} of A , there is a corresponding equivalence relation: we set $x \sim y$, if x and y belong to the same part of \mathcal{P} .

A Matter of Identification

A Matter of Identification

Example 3

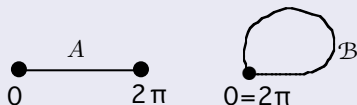
Let $A = [0, 2\pi]$



A Matter of Identification

Example 3

Let $A = [0, 2\pi]$

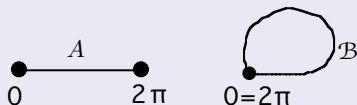


- The quotient space $\mathcal{B} = \{[0, 2\pi]\} \cup \{x : x \in (0, 2\pi)\}$ is homeomorphic to S^1 .

A Matter of Identification

Example 3

Let $A = [0, 2\pi]$

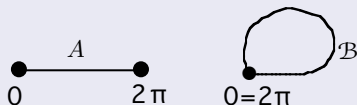


- The quotient space $B = \{[0, 2\pi]\} \cup \{x : x \in (0, 2\pi)\}$ is homeomorphic to S^1 .
- It is often described simply by saying it **identifies** the endpoints 0 and 2π of $[0, 2\pi]$.

A Matter of Identification

Example 3

Let $A = [0, 2\pi]$

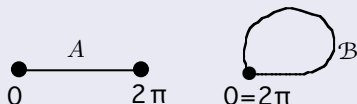


- The quotient space $B = \{\{0, 2\pi\}\} \cup \{\{x\} : x \in (0, 2\pi)\}$ is homeomorphic to S^1 .
- It is often described simply by saying it **identifies** the endpoints 0 and 2π of $[0, 2\pi]$.

A Matter of Identification

Example 3

Let $A = [0, 2\pi]$



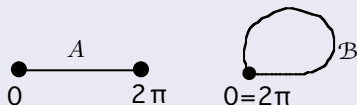
- The quotient space $B = \{[0, 2\pi]\} \cup \{[x] : x \in (0, 2\pi)\}$ is homeomorphic to S^1 .
- It is often described simply by saying it **identifies** the endpoints 0 and 2π of $[0, 2\pi]$.

This shortcut is often used to define quotients:

A Matter of Identification

Example 3

Let $A = [0, 2\pi]$



- The quotient space $B = \{[0, 2\pi]\} \cup \{[x] : x \in (0, 2\pi)\}$ is homeomorphic to S^1 .
- It is often described simply by saying it **identifies** the endpoints 0 and 2π of $[0, 2\pi]$.

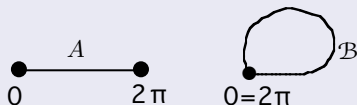
This shortcut is often used to define quotients:

- State which points **do** get identified.

A Matter of Identification

Example 3

Let $A = [0, 2\pi]$



- The quotient space $\mathcal{B} = \{\{0, 2\pi\}\} \cup \{\{x\} : x \in (0, 2\pi)\}$ is homeomorphic to S^1 .
- It is often described simply by saying it **identifies** the endpoints 0 and 2π of $[0, 2\pi]$.

This shortcut is often used to define quotients:

- State which points **do** get identified.
- Assume other points are **not** identified.

The Quotient Game

To test your intuition about simple quotients, we play a game:

The Quotient Game

To test your intuition about simple quotients, we play a game:

The Rules

- I give you a space and describe which points are identified.
- You decide which well-known space is homeomorphic to this quotient.

The Quotient Game

To test your intuition about simple quotients, we play a game:

The Rules

- I give you a space and describe which points are identified.
- You decide which well-known space is homeomorphic to this quotient.

Example 4

The closed square $[0, 1] \times [0, 1]$ in \mathbb{R}^2 with all pairs of points of the form $\{(0, y), (1, y)\}$ identified.

The Quotient Game

To test your intuition about simple quotients, we play a game:

The Rules

- I give you a space and describe which points are identified.
- You decide which well-known space is homeomorphic to this quotient.

Example 4

The closed square $[0, 1] \times [0, 1]$ in \mathbb{R}^2 with all pairs of points of the form $\{(0, y), (1, y)\}$ identified. **Cylinder**.

The Quotient Game

To test your intuition about simple quotients, we play a game:

The Rules

- I give you a space and describe which points are identified.
- You decide which well-known space is homeomorphic to this quotient.

Example 4

The closed square $[0, 1] \times [0, 1]$ in \mathbb{R}^2 with all pairs of points of the form $\{(0, y), (1, y)\}$ identified. **Cylinder**.

Example 5

The closed ball $\overline{B}_1((0, 0))$ in \mathbb{R}^2 with all points on the “boundary” circle S^1 identified.

The Quotient Game

To test your intuition about simple quotients, we play a game:

The Rules

- I give you a space and describe which points are identified.
- You decide which well-known space is homeomorphic to this quotient.

Example 4

The closed square $[0, 1] \times [0, 1]$ in \mathbb{R}^2 with all pairs of points of the form $\{(0, y), (1, y)\}$ identified. **Cylinder**.

Example 5

The closed ball $\overline{B}_1((0, 0))$ in \mathbb{R}^2 with all points on the “boundary” circle S^1 identified. **Sphere**.

Example 6

$[0, 1]$ with all points in $[0, \frac{1}{2}]$ identified.

Example 6

$[0, 1]$ with all points in $[0, \frac{1}{2}]$ identified. **Closed interval.**

Example 6

$[0, 1]$ with all points in $[0, \frac{1}{2}]$ identified. **Closed interval**. If we instead identify all the points of $[0, 1)$ we get a two-point non-Hausdorff space.

Example 6

$[0, 1]$ with all points in $[0, \frac{1}{2}]$ identified. **Closed interval**. If we instead identify all the points of $[0, 1)$ we get a two-point non-Hausdorff space. Exercise: describe the topology of \mathbb{R} with $\mathbb{R} \setminus \mathbb{Q}$ identified.

The Game Goes On ...

Example 6

$[0, 1]$ with all points in $[0, \frac{1}{2}]$ identified. **Closed interval**. If we instead identify all the points of $[0, 1)$ we get a two-point non-Hausdorff space. Exercise: describe the topology of \mathbb{R} with $\mathbb{R} \setminus \mathbb{Q}$ identified.

Example 7

The closed rectangle $[0, 4] \times [0, 1]$ in \mathbb{R}^2 with all pairs of points of the form $\{(0, y), (4, 1 - y)\}$ identified.

The Game Goes On ...

Example 6

$[0, 1]$ with all points in $[0, \frac{1}{2}]$ identified. **Closed interval**. If we instead identify all the points of $[0, 1)$ we get a two-point non-Hausdorff space. Exercise: describe the topology of \mathbb{R} with $\mathbb{R} \setminus \mathbb{Q}$ identified.

Example 7

The closed rectangle $[0, 4] \times [0, 1]$ in \mathbb{R}^2 with all pairs of points of the form $\{(0, y), (4, 1 - y)\}$ identified. **Möbius band**.

The Game Goes On ...

Example 6

$[0, 1]$ with all points in $[0, \frac{1}{2}]$ identified. **Closed interval**. If we instead identify all the points of $[0, 1)$ we get a two-point non-Hausdorff space. Exercise: describe the topology of \mathbb{R} with $\mathbb{R} \setminus \mathbb{Q}$ identified.

Example 7

The closed rectangle $[0, 4] \times [0, 1]$ in \mathbb{R}^2 with all pairs of points of the form $\{(0, y), (4, 1 - y)\}$ identified. **Möbius band**.

Example 8

The closed square $[0, 1] \times [0, 1]$ in \mathbb{R}^2 with pairs of points of the forms $\{(0, y), (1, y)\}$ and $\{(x, 0), (x, 1)\}$ identified.

The Game Goes On ...

Example 6

$[0, 1]$ with all points in $[0, \frac{1}{2}]$ identified. **Closed interval**. If we instead identify all the points of $[0, 1)$ we get a two-point non-Hausdorff space. Exercise: describe the topology of \mathbb{R} with $\mathbb{R} \setminus \mathbb{Q}$ identified.

Example 7

The closed rectangle $[0, 4] \times [0, 1]$ in \mathbb{R}^2 with all pairs of points of the form $\{(0, y), (4, 1 - y)\}$ identified. **Möbius band**.

Example 8

The closed square $[0, 1] \times [0, 1]$ in \mathbb{R}^2 with pairs of points of the forms $\{(0, y), (1, y)\}$ and $\{(x, 0), (x, 1)\}$ identified. **Torus**. [Animation](#)

Example 9

The closed square $[0, 1] \times [0, 1]$ in \mathbb{R}^2 with pairs of points of the forms $\{(0, y), (1, y)\}$ and $\{(x, 0), (1 - x, 1)\}$ identified.

Example 9

The closed square $[0, 1] \times [0, 1]$ in \mathbb{R}^2 with pairs of points of the forms $\{(0, y), (1, y)\}$ and $\{(x, 0), (1 - x, 1)\}$ identified. **Klein bottle**. [Animation](#)

Example 9

The closed square $[0, 1] \times [0, 1]$ in \mathbb{R}^2 with pairs of points of the forms $\{(0, y), (1, y)\}$ and $\{(x, 0), (1 - x, 1)\}$ identified. **Klein bottle**. [Animation](#)

Example 10

The closed square $[0, 1] \times [0, 1]$ in \mathbb{R}^2 with pairs of points of the forms $\{(0, y), (1, 1 - y)\}$ and $\{(x, 0), (1 - x, 1)\}$ identified.

Example 9

The closed square $[0, 1] \times [0, 1]$ in \mathbb{R}^2 with pairs of points of the forms $\{(0, y), (1, y)\}$ and $\{(x, 0), (1 - x, 1)\}$ identified. **Klein bottle**. [Animation](#)

Example 10

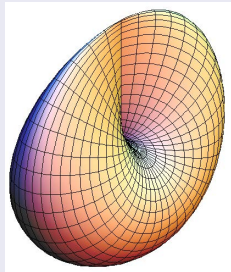
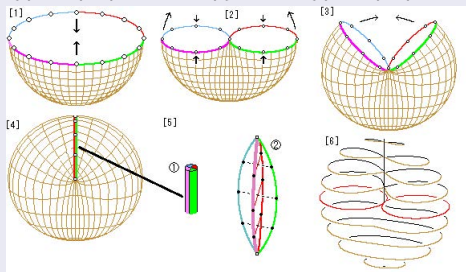
The closed square $[0, 1] \times [0, 1]$ in \mathbb{R}^2 with pairs of points of the forms $\{(0, y), (1, 1 - y)\}$ and $\{(x, 0), (1 - x, 1)\}$ identified. **Projective plane**.

Example 9

The closed square $[0, 1] \times [0, 1]$ in \mathbb{R}^2 with pairs of points of the forms $\{(0, y), (1, y)\}$ and $\{(x, 0), (1 - x, 1)\}$ identified. **Klein bottle**. [Animation](#)

Example 10

The closed square $[0, 1] \times [0, 1]$ in \mathbb{R}^2 with pairs of points of the forms $\{(0, y), (1, 1 - y)\}$ and $\{(x, 0), (1 - x, 1)\}$ identified. **Projective plane**.

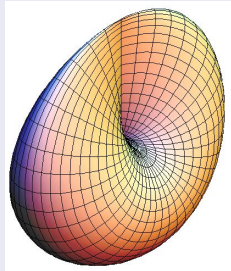
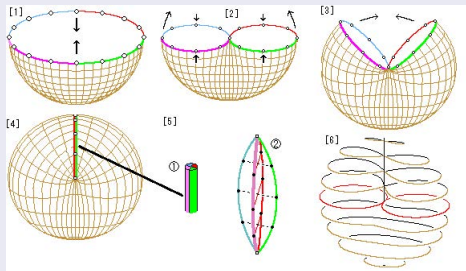


Example 9

The closed square $[0, 1] \times [0, 1]$ in \mathbb{R}^2 with pairs of points of the forms $\{(0, y), (1, y)\}$ and $\{(x, 0), (1 - x, 1)\}$ identified. **Klein bottle**. [Animation](#)

Example 10

The closed square $[0, 1] \times [0, 1]$ in \mathbb{R}^2 with pairs of points of the forms $\{(0, y), (1, 1 - y)\}$ and $\{(x, 0), (1 - x, 1)\}$ identified. **Projective plane**.



Exercise: What do we get if we identify the bounding circles of two discs? of a Möbius band and a disc? of two Möbius bands?

Self Preservation

Self Preservation

Continuity of $\pi : A \rightarrow B$ is very useful:

Self Preservation

Continuity of $\pi : A \rightarrow B$ is very useful:

Theorem 1 (Properties of Quotients)

Let B be a quotient of a topological space (A, S) .

Self Preservation

Continuity of $\pi : A \rightarrow B$ is very useful:

Theorem 1 (Properties of Quotients)

Let B be a quotient of a topological space (A, S) .

- 1 *If A is connected, so is B .*
- 2 *If A is path connected, so is B .*
- 3 *If A is compact, so is B .*

Self Preservation

Continuity of $\pi : A \rightarrow B$ is very useful:

Theorem 1 (Properties of Quotients)

Let B be a quotient of a topological space (A, S) .

- 1 *If A is connected, so is B .*
- 2 *If A is path connected, so is B .*
- 3 *If A is compact, so is B .*

Unfortunately:

Self Preservation

Continuity of $\pi : A \rightarrow B$ is very useful:

Theorem 1 (Properties of Quotients)

Let B be a quotient of a topological space (A, S) .

- 1 *If A is connected, so is B .*
- 2 *If A is path connected, so is B .*
- 3 *If A is compact, so is B .*

Unfortunately:

- Quotients of Hausdorff spaces need not be Hausdorff (see Example 6).

Self Preservation

Continuity of $\pi : A \rightarrow B$ is very useful:

Theorem 1 (Properties of Quotients)

Let B be a quotient of a topological space (A, S) .

- 1 If A is connected, so is B .
- 2 If A is path connected, so is B .
- 3 If A is compact, so is B .

Unfortunately:

- Quotients of Hausdorff spaces need not be Hausdorff (see Example 6).
- Non-Hausdorff spaces may have Hausdorff quotients (all to a point).

Self Preservation

Continuity of $\pi : A \rightarrow B$ is very useful:

Theorem 1 (Properties of Quotients)

Let B be a quotient of a topological space (A, S) .

- 1 If A is connected, so is B .
- 2 If A is path connected, so is B .
- 3 If A is compact, so is B .

Unfortunately:

- Quotients of Hausdorff spaces need not be Hausdorff (see Example 6).
- Non-Hausdorff spaces may have Hausdorff quotients (all to a point).
- The natural projection map π may fail to be open (exercise).

Self Preservation

Continuity of $\pi : A \rightarrow B$ is very useful:

Theorem 1 (Properties of Quotients)

Let B be a quotient of a topological space (A, S) .

- 1 If A is connected, so is B .
- 2 If A is path connected, so is B .
- 3 If A is compact, so is B .

Unfortunately:

- Quotients of Hausdorff spaces need not be Hausdorff (see Example 6).
- Non-Hausdorff spaces may have Hausdorff quotients (all to a point).
- The natural projection map π may fail to be open (exercise).
- The natural projection map π may fail to be closed (exercise).

Some Results

Although the natural projection map π may fail to be open or closed, there are some partial results.

Some Results

Although the natural projection map π may fail to be open or closed, there are some partial results.

Definition 4

Let \mathcal{B} be a quotient of a topological space (A, \mathcal{S}) and let $\pi : A \rightarrow \mathcal{B}$ denote the natural projection. We say that a subset $U \subset A$ is **π -saturated** if $\pi^{-1}(\{z\}) \subset U$ for all $z \in \pi(U)$.

Some Results

Although the natural projection map π may fail to be open or closed, there are some partial results.

Definition 4

Let \mathcal{B} be a quotient of a topological space (A, \mathcal{S}) and let $\pi : A \rightarrow \mathcal{B}$ denote the natural projection. We say that a subset $U \subset A$ is **π -saturated** if $\pi^{-1}(\{z\}) \subset U$ for all $z \in \pi(U)$.

Theorem 2 (π -saturated open sets)

For all open π -saturated sets $U \subset A$, the image $\pi(U)$ is open in \mathcal{B} .

Some Results

Although the natural projection map π may fail to be open or closed, there are some partial results.

Definition 4

Let \mathcal{B} be a quotient of a topological space (A, \mathcal{S}) and let $\pi : A \rightarrow \mathcal{B}$ denote the natural projection. We say that a subset $U \subset A$ is **π -saturated** if $\pi^{-1}(\{z\}) \subset U$ for all $z \in \pi(U)$.

Theorem 2 (π -saturated open sets)

For all open π -saturated sets $U \subset A$, the image $\pi(U)$ is open in \mathcal{B} .

Proof: as U is saturated, $\pi^{-1}(\pi(U)) = U$.

Some Results

Although the natural projection map π may fail to be open or closed, there are some partial results.

Definition 4

Let \mathcal{B} be a quotient of a topological space (A, \mathcal{S}) and let $\pi : A \rightarrow \mathcal{B}$ denote the natural projection. We say that a subset $U \subset A$ is **π -saturated** if $\pi^{-1}(\{z\}) \subset U$ for all $z \in \pi(U)$.

Theorem 2 (π -saturated open sets)

For all open π -saturated sets $U \subset A$, the image $\pi(U)$ is open in \mathcal{B} .

Proof: as U is saturated, $\pi^{-1}(\pi(U)) = U$.

Theorem 3 (Hausdorff Quotients)

Let \mathcal{B} be a quotient of a topological space (A, \mathcal{S}) . If \mathcal{B} is Hausdorff, then for each $x \in \mathcal{B}$, $\pi^{-1}(x)$ is closed in A .

Some Results

Although the natural projection map π may fail to be open or closed, there are some partial results.

Definition 4

Let \mathcal{B} be a quotient of a topological space (A, \mathcal{S}) and let $\pi : A \rightarrow \mathcal{B}$ denote the natural projection. We say that a subset $U \subset A$ is **π -saturated** if $\pi^{-1}(\{z\}) \subset U$ for all $z \in \pi(U)$.

Theorem 2 (π -saturated open sets)

For all open π -saturated sets $U \subset A$, the image $\pi(U)$ is open in \mathcal{B} .

Proof: as U is saturated, $\pi^{-1}(\pi(U)) = U$.

Theorem 3 (Hausdorff Quotients)

Let \mathcal{B} be a quotient of a topological space (A, \mathcal{S}) . If \mathcal{B} is Hausdorff, then for each $x \in \mathcal{B}$, $\pi^{-1}(x)$ is closed in A .

Proof: x' is open in \mathcal{B} by Hausdorffity, hence $\pi^{-1}(x')$ is open in A , as π is continuous. Then $(\pi^{-1}(x'))'$ is closed in A . But $(\pi^{-1}(x'))' = \pi^{-1}(x)$.

Some Results...

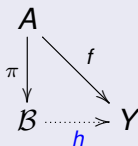
And a final result

Lemma 1 (sort of universality)

Let \mathcal{B} be a quotient of a space (A, \mathcal{S}) , let (Y, \mathcal{T}) be a space and let $f : A \rightarrow Y$ be a continuous map satisfying

$$\pi(x) = \pi(y) \Rightarrow f(x) = f(y).$$

Then $h : \mathcal{B} \rightarrow Y : \pi(x) \mapsto f(x)$ is well defined and continuous. If f is onto, so is h .



Some Results...

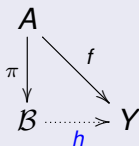
And a final result

Lemma 1 (sort of universality)

Let \mathcal{B} be a quotient of a space (A, \mathcal{S}) , let (Y, \mathcal{T}) be a space and let $f : A \rightarrow Y$ be a continuous map satisfying

$$\pi(x) = \pi(y) \Rightarrow f(x) = f(y).$$

Then $h : \mathcal{B} \rightarrow Y : \pi(x) \mapsto f(x)$ is well defined and continuous. If f is onto, so is h .



Proof: by definition (final topology is universal, all that).